

13th CDTI - NEDO Joint Workshop
“AI-Equipped Collaborative Robot Technology”
December 11, 2025 Tokyo



Artificial Intelligence and robotics for
rehabilitation, care and education

Fernando Fernández
CSO Inrobics Social Robotics



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robots for a better quality of life

Professor Universidad Carlos III de MADRID





Alma & Inrobics



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Alma & Inrobics



About Inrobics: founders, vision and mission

The Founders

10 years building
innovative social
technologies to impact
on people's quality of
life, together with a
highly qualified team

Spin off
uc3m
Universidad
Carlos III
de Madrid



José Carlos Pulido
CEO and Founder
Ph.D. in Computer Science

MBA in Digital Health.
Postdoc at University of Southern
California. Human robot interaction,
AI and e-Health.



José Carlos González
CTO and Founder
Ph.D. in Computer Science

Postdoctoral stay at Carnegie
Mellon University
Robotic architectures and back
end processes expert



Fernando Fernández
CSO and Founder
Ph.D. in Computer Science

Faculty of the Computer Science
Dept. at UC3M
20+ years leading AI and robotics
R&D projects





About Inrobics: some data



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Management



José Carlos Pulido
CEO / Founder



José Carlos González
CTO / Founder



Fernando Fernández
CSO / Founder



Rodrigo Alarcón
Data Scientist & NLP



Carmen Díaz
HRI Engineer

Clinical and Regulatory



Fuensanta García
Clinical Advisor
Quality & Reg.



Irene Domínguez
OT &
Clinical Advisor

Software development



María Almeida
Robotic Engineer



Víctor Cereijo
Data Engineer



Raúl Agreda
RV Designer

Marketing & Sales



Tania Tejada
Business Strategy &
Internationalization



Ana Moreno
Operations



Ana Albendea
Marketing &
Communications



Daniela Paucar
Internationalization



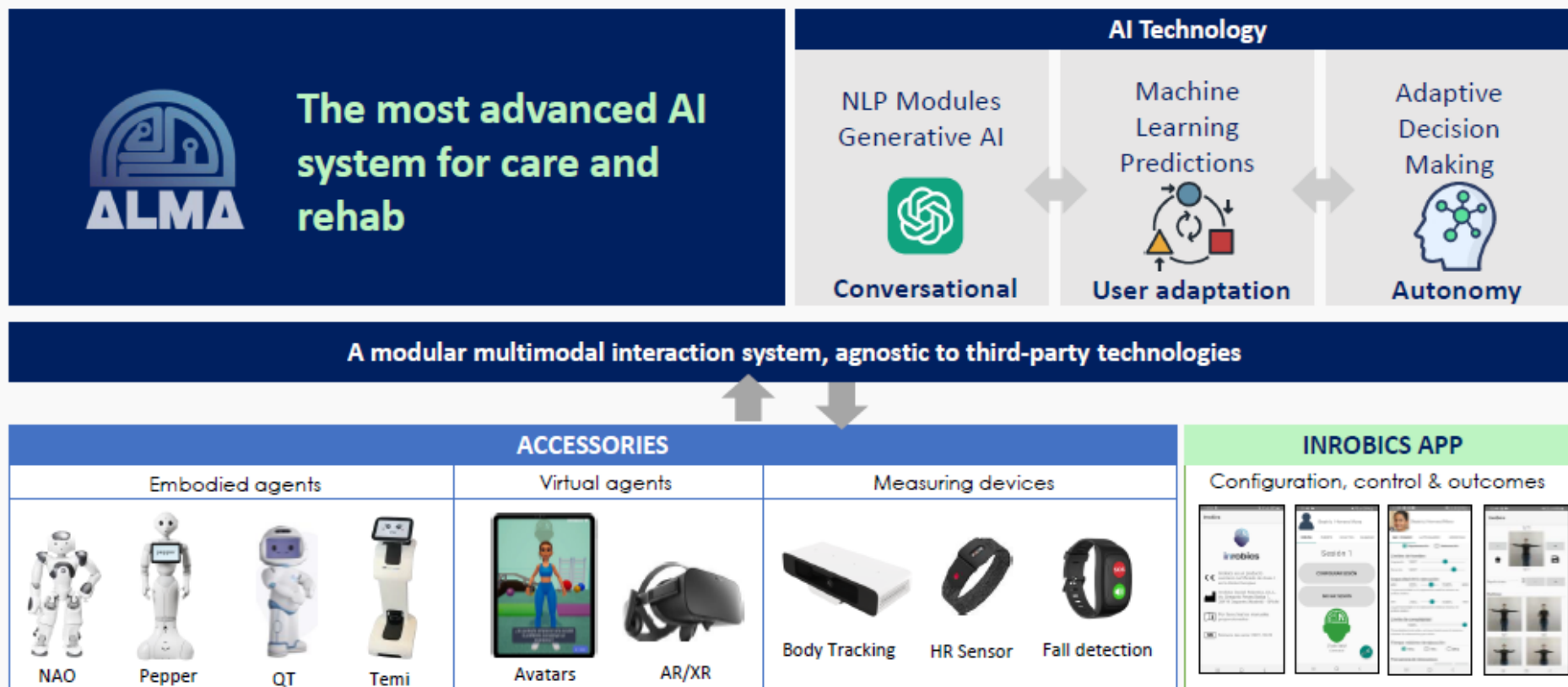


Products, services, technologies of the company



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Our Social AI





Products, services, technologies of the company



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Class I, Reg No.
RPS/777/2021

Product Portfolio

Inroboics Rehab Clinic ®

A social robot for physical and cognitive stimulation



Inroboics Analytics ®

An Advanced Analytics and Reporting System



Inroboics Rehab Virtual ®

A virtual robot companion for home rehabilitation





Main challenges and solutions in the project/case presented



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Inroboics Care ®

Clara Inroboics' 24/7 virtual assistant for home use. From a **mobile or tablet**, it lets users hold **conversations**, **connect** with family, set **reminders**, and perform personalized **physical** and **cognitive exercises**—autonomously

Welcome! *Clara*



Using social AI, *Clara* adapts to each user's needs and progress—ideal **for healthy seniors** or those with mild to **advanced** cognitive challenges

Scalable and **modular**, Inroboics fits into existing care services, promoting **autonomy**, **reducing loneliness**, and **supporting families** with peace of mind

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Ideas for a Japan – Inrobics collaboration



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- ✓ **Medical Vision System Optimization:** Collaborate to integrate other accessories, like lenses and cameras into Inrobics' Computer Vision (CV) sensors.
- ✓ **Advanced Behavioral AI for Safety and Assessment:** Integrate **Behavior Recognition AI** into Inrobics' Alma engine.
- ✓ **Hardware Platform Expansion:** Collaborate to integrate the Alma software (Inrobics' AI) onto diverse robotic platforms.
- ✓ **Strategic Asian Distribution Alliance:** Establish an agreement where Japanese companies serve as a **strategic distributor or sales partner** for the certified Inrobics Rehab and Care platforms in Japan and the broader Asian market.



Ideas for a Japan – Inrobics collaboration



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- ✓ **Joint R&D for Clinical Support Tools (B2B):** Create a joint R&D project to design semi-autonomous robotic assistants that, using optical components and hardware expertise, support clinical staff in non-therapeutic tasks (e.g., material handling, simplified patient monitoring) within hospitals, further reducing the professional workload.
- ✓ **Educational Robotics for ASD/Special Needs:** Integrate the **Alma AI's relational/social skills training modules** (used in early care/ASD) into other educational robots.
- ✓ **Recognizing, analyzing, and predicting human behavior with multi-camera tracking capability:** AI Model Enhancement (with **high-accuracy human pose and trajectory estimation**, or complex, clinical-grade gait analysis) and **Spatial Awareness & Safety** (trigger safety alerts and record objective data across an entire therapeutic space, not just one camera point.)

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Thank you



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